



Short Communication

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Discovering Hidden Offshore Lighting Structures with Multiyear Low-Light Imaging Satellite Data



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Abstract

The NASA/NOAA Visible Infrared Imaging Radiometer Suite (VIIRS) day/night band (DNB) has a capability to detect lighting present at the earth's surface. This low-light imaging capability was built to satisfy a requirement from meteorologists to detect clouds at night in the visible based on reflected moonlight. On land, human settlements are the dominant source of DNB detected surface lighting. Lights are also detected offshore primarily arising from fishing boats using lights to attract catch. In 2015, the Earth Observation Group developed the VIIRS Boat Detection (VBD) product and today several fishery agencies use VBD data to monitor fishing activity and compliance with closures. Recently EOG compiled the full record VBD detections as a 15 arc second global grid. The record spans 2012-2021 in Asia and 2017-2021 elsewhere. Upon reviewing the multiyear accumulation of VBD detections we were surprised to find a diversity of previously unseen lighting features [1]. These structures are not evident in VBD from single nights but are only revealed by accumulating the detections across a year or more. The additional features include lit platforms, transit lanes, and vessel anchorages associated with ports and passage straits. Another surprising finding is geopolitical divisions in the density of cumulative vessel detections. In this paper we provide a look into one of the densest areas of VBD detections in the world, from the Yellow Sea, East China Sea and Sea of Japan (East Sea).

Keywords: VIIRS; Day/night band; Vessel detection; Fishing grounds; Light pollution

Abbreviations: DNB: Day/Night band; DMSP: Defense Meteorological Satellite Program; OLS: Operational Linescan System; VIIRS: Visible Infrared Imaging Radiometer Suite; EOG: Earth Observation Group; JPSS: Joint Polar Satellite System; USAID: United States Agency for International Development; VBD: VIIRS boat detection; VMS: Vessel monitoring system; AIS: Automatic Identification System; QF: Quality Flags

Introduction

It has been known since the 1970's that heavily lit fishing boats can be detected with nighttime visible low-light imaging data collected by polar-orbiting meteorological sensors [2]. The two-sensor series having low-light imaging capabilities include the U.S. Air Force Defense Meteorological Satellite Program (DMSP) Operational Linescan System (OLS) and the NASA/NOAA Visible Infrared Imaging Radiometer Suite (VIIRS). These sensors use light intensification to enable the detection of moonlit clouds at night - to satisfy a requirement from meteorologists for day

and night visible and thermal imagery of clouds. The OLS digital archive extends from 1992 to the present and collects relatively coarse resolution (2.7km ground sample distance) global data. The VIIRS sensor provides key improvements [3] in low-light imaging from 2012 to the present and the pixel resolution (742m × 742m) is finer and has in-flight calibration to radiance units. In 2015, the Earth Observation Group (EOG) developed the VIIRS boat detection (VBD) algorithm [4] with support from NOAA's Joint Polar Satellite System (JPSS) proving ground program and United States Agency for International Development (USAID). The

VBD data were produced in near real-time, and the nightly record extends back to April 2012 in Asia and back to 2017 outside of Asia. In addition to the nightly product, the EOG also made monthly and annual summary grids.

Several fishery agencies rely on VIIRS boat detection (VBD) data in monitoring fishing activity and detection of vessels fishing in closures [5] and marine protected areas. This includes the Philippines, Indonesia, Thailand, Japan and South Korea. Maritime domain awareness relies extensively on vessel location data from services such as VMS (vessel monitoring system) and AIS (automatic identification system). Several studies have shown that VBD detects “dark” fishing vessels operating without VMS or AIS [6,7]. In many cases, vessels detected in VBD but lacking signals from VMS or AIS are below the tonnage levels set for the GPS beacons.

In order to define the outlines of fishing grounds and temporal patterns of usage, we produce both monthly and annual summary grids. We recently made a global long-term VBD cumulative detection grid and report here on some of our findings.

Methods

All of the nightly VBD products were ingested in a database which facilitates extractions based on user specified criteria. From the database, EOG produced long term summary grids spanning 2012 to present for Asia and 2017 to present in other parts of the world. Each VBD pixel is labeled based on its sharpness and location. The labels are referred to as quality flags or QF. We built

a multiyear cumulative detection grid using QF 1,2,3,8 and 10. This corresponds to the labels of strong, weak, blurry, recurring, platforms and flares [4,8]. The detections were accumulated in a global 15 arc second grid, whose grid cells are approximately half km on a side at the equator. The grids produced include number of detections, number of valid VIIRS observations, and average radiance. The percentage frequency of detection is calculated by dividing the number of detections by the number of valid observations. The percentage frequency of detection normalizes for the differences in the number of years of data in Asia and other parts of the world. EOG also developed methods to extract temporal profiles for specific spatial features found in the summary grids.

Results

Figure 1 shows the percent frequency of VBD detection for one the densest parts of the world for VBD, the Yellow Sea, East China Sea, and Sea of Japan (East Sea). The fishing grounds show up as large light gray features. In other parts of the world, fishing grounds tend to appear as amorphous clusters. In some cases, fishing vessels operate in international waters and are pressed against the EEZ boundary of a country that prohibits foreign vessel fishing in their EEZ. This is the case in Peru, where international squid fishing boats operate just outside of Peru’s EEZ line. In this area it is possible to see changes in the density of VBD detections along the Japan – South Korea EEZ, the North and South Korea EEZ boundaries, and the EEZ boundary between North Korea and Russia (Figure 2).

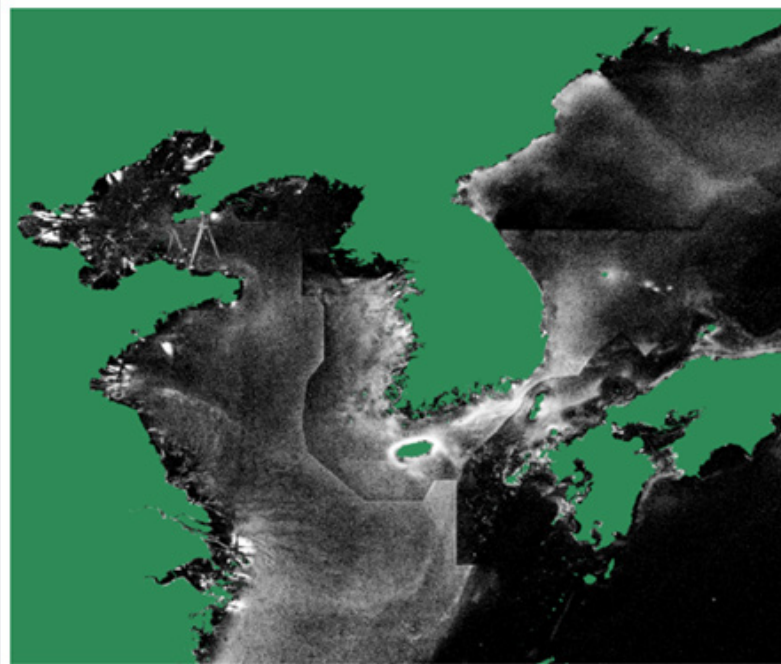


Figure 1: Contrast enhanced percent frequency of detection derived from the cumulative VBD detections from 2012-2021 for the Yellow Sea, East China Sea, and Sea of Japan (East Sea).

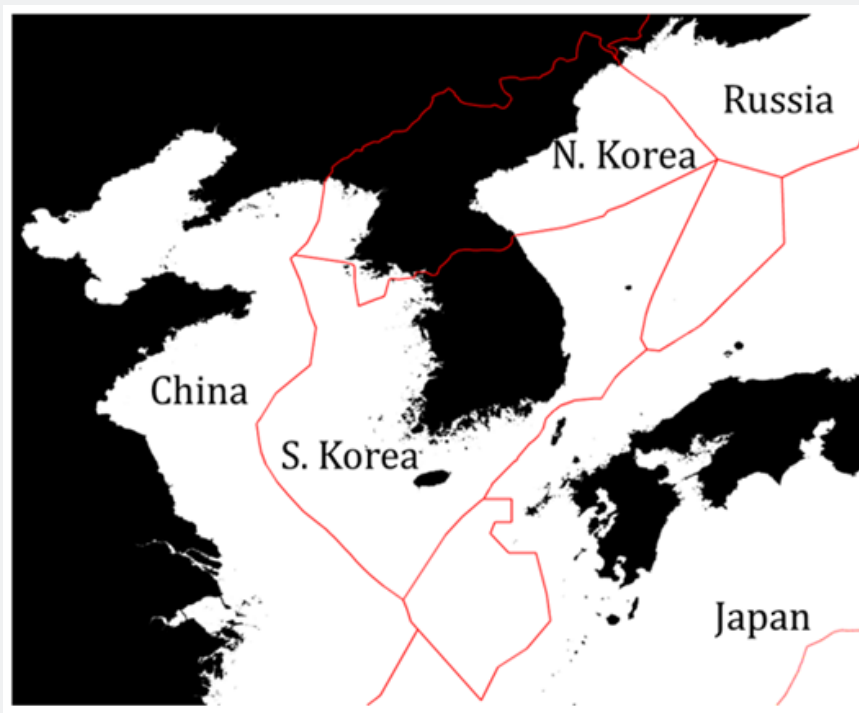


Figure 2: EEZ lines in the study area.

This Asia area is unique in the appearance of linear features dividing fishing ground that have no correspondence to EEZ lines. These trace back to bilateral agreements between South Korea with China and Japan with China that permits Chinese fishing boats to operate in other country's EEZ waters up to the lines visible in the image.

While fishing grounds cover that largest area having VBD detections, the percent frequency of detection for an individual half kilometer grid cell in fishing grounds is small - rarely exceeding 1% over. There are compact clusters of non-fishing VBD features, mostly near shore having higher percent frequencies of detection, in the range of 1-3%. The non-fishing features include anchorages, platforms, and aquaculture. These show up as white on the contrast enhance image in figure 1. Note the large number of vessel anchorages along the shore of China, associated with the export of manufactured products. Another type of feature that can be seen in the northern end of the Yellow Sea are linear features going from port to port. These are passenger ferry transit lanes. The most prominent in this case is the ferry line operating between Dalian and Yantai, China.

Conclusion

The ocean at night is a vast dark palette where any lighting can be readily detected by the VIIRS day/night band. While VIIRS boat detection data are produced nightly, they hold no hint of the

sharply defined structures shown in figure 1. The structures are revealed through the lens of time - by accumulating detections over multiple years.

Acknowledgment

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